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Aeroespacial y Defensa





Simumak is a Spanish company with an international presence belonging to everis Aerospace and Defense, which, in turn, is part of the NTT DATA group. Simumak has a long experience developing didactic simulation solutions for the Automotive, Construction, Mining, Logistics and Defense sectors.

Simumak develops 100% of its solutions in an affordable way, focusing on the specific needs of customers, combining the use of new technologies with the real needs of its customers.

# How to operate it?



**Simumak Immersive Simulators** is the division from which we develop the software and hardware of cockpit simulators specifically designed for students to learn how to operate vehicles or machines. Boost the performance of your operators or qualify more prepared students thanks to our training plans on board Simumak simulators.

## How does it work?



From the **Simumak VR Training** division, we design training plans adapted to the needs of the client, with the aim that the students are able to assimilate theoretical-practical knowledge, functions, or processes, using, as hardware, high quality and very low cost commercial products (Oculus Go). Optimize the assimilation of your processes or improve the understanding of your students through our immersive training tools.





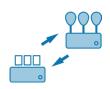
# MINESIM AVR SIMULATOR

Our goal is to maximize your profit by increasing the safety and productivity of your equipment.

After more than 15 years of designing virtual trainings tools, we have developed a product adapted to your needs with which you will be able to achieve real, measurable results that will optimize the operation of your company.



Fewer accidents, higher productivity in the warehouse, more profitable work cycles, recruiting, creating and retaining talented operators through specific training programmes are just some of the examples where we can help you through our **virtual training tools.** 



Simumak has developed **MINESIM AVR, a multi-machine simulator** specially designed to meet the needs of companies in the mining sector.

MINESIM AVR can easily be configured as a **crawler excavator** (front or backhoe), loader shovel or dumper truck from the same hardware. This will allow training to be given to different groups of professionals from a single simulation station, thus facilitating the rapid amortization of the investment made.



MINESIM AVR incorporates a revolutionary **AVR (Augmented Virtual Reality) vision system** that immerses the operator in a completely virtual environment, in which he has absolute freedom to modify his perspective, also allowing him to see his own hands and the controls of the cabin that surround him and with which he has to interact. Never before has a machine simulator come so close to reality.



MINESIM AVR can operate stand-alone, but it can also be integrated with the **INSTRUCTOR STATION**, the student and exercise management platform (**SOCRATES**) and the exercises generator (**Training Manager**), which will allow you to create training plans very quickly and at a very low cost.

We know that there are many different needs, even within the same company, so we have developed a product range with different models to suit different scenarios. From the MINESIM AVR PORTABLE, designed to be easily transported and deployed on the student's own table, to the MINESIM AVR GOLD, which with its set of real controls and its 3DOF motion platform has been designed to meet the most demanding immersion needs.

### SIMUMAK SIMULATION ECOSYSTEM



#### **SOCRATES**

- Students and instructors management
- Exercises settings
- Sessions scheduling
- Results displaying



#### **TRAINING MANAGER**

- Exercises creation and edition
- Generation of specific situations
- Guided learning plan



#### **SIMFLEET MANAGER**

- Simulators management
- HW and SW updates
- Maintenance
- Remote issues management



#### **OBSERVER STATION**

- It may be located in another room.
- Learning extension
- It allows the students to observe the development of the practice carried out in the simulator

#### **INSTRUCTOR STATION**

- Formed by three screens, a computer and a printer
- Telemetry application
- Visualization and communication with the student
- Modification of simulation conditions in real time (events, breakdowns, modification of weather conditions...)
- Interaction in real time with another vehicle thanks to the cooperative driving mode

#### **SIMULATION STATION**

- High immersion: realistic HW and SW
- Customizable learning program
- 3DOF movement platform to guarantee a complete immersive feeling
- Several machines in one simulator



### **AVAILABLE VERSIONS**

This simulator is highly configurable, and able to be adjusted to client's needs. This simulator offers three kinds of versions.



#### **MINESIM OYD**

The option OYD (On Your Desktop) consists on one notebook, VR headset and controls (joysticks, steering wheel and pedals). It offers an immersive solution, creative and economic, designed to be easily portable.

The installation is very simple and takes up very little space, allowing its use in conventional training classroom that in a few minutes become advanced simulation centers where all students can practice on board a simulator.

When the VR headset is put on, the students sit on a machine thanks to the AVR system.



#### **MINESIM AVR SILVER**

MINESIM AVR Silver offers a very realistic immersion thanks to the machine control system, which imitates the real controls. This system allows the configuration as a forklift truck or as a side reach truck, by mean of a simple change of controls that can be carried out by the instructor himself.

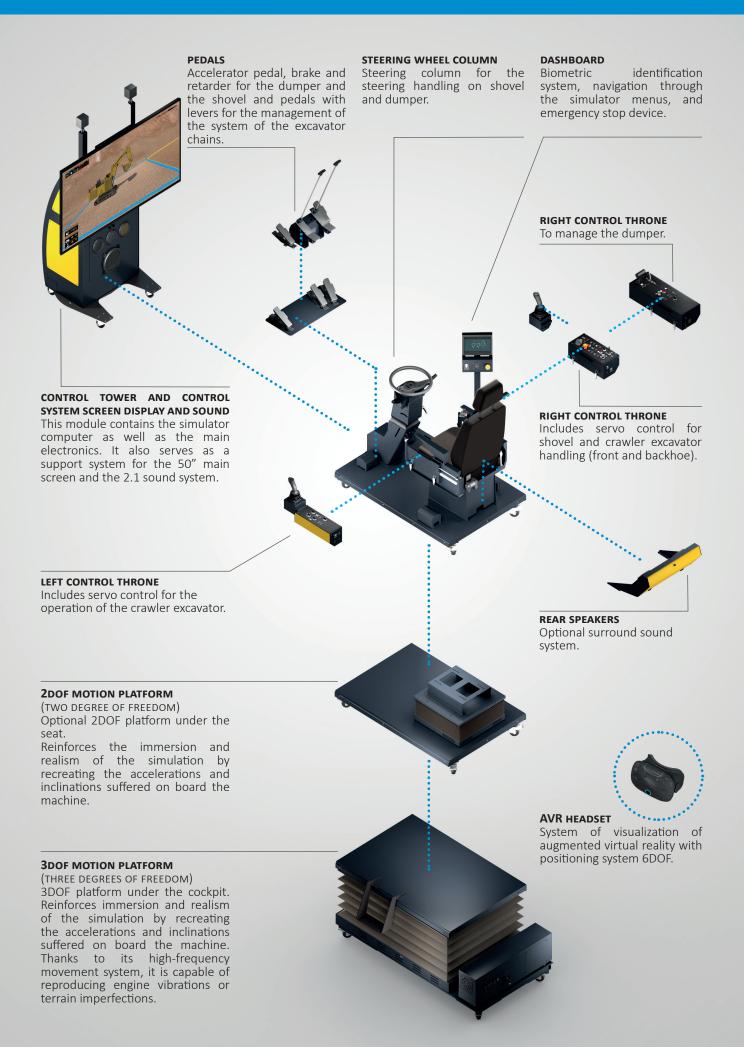
Under the seat it is possible to install a 2DOF motion platform that will move the operator slightly, giving him a sensation of immersion and almost absolute realism.



#### **MINESIM AVR GOLD**

The main difference between the MINESIM AVR Silver and the **MINESIM AVR Gold** is that the latter mounts under its cockpit (not just under the seat) a 3DOF platform(3 degrees of freedom: heave / roll / pitch) that represents with great fidelity the inertial expensione on board the machine.

In a few seconds the operator will forget that he is on a simulator and will focus on carrying out the work or exercise that has been entrusted to him. The immersion is very complete and this allows students to spend a lot of time on board the simulator without feeling fatigue or discomfort.





### TECHNOLOGY AT YOUR SERVICE

MINESIM AVR is equipped with the most advanced technologies that turn this simulation experience into a realistic and useful learning one, making this product an essential tool for training.



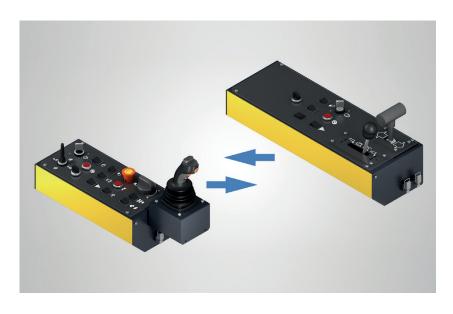
#### **HIGH IMMERSION AVR**

No more seeing reality through a screen. Thank to Augmented Virtual Reality (AVR), looking in any direction, changing the perspective and being able to interact with the cockpit that surrounds us is possible. The sensation of immersion cannot be greater.



#### **EARTH PHYSICS SYSTEM EAPS**

Thanks to the "Earth Advanced Physics System" and its multithreaded technology, the feel of digging and the behaviour of the earth become fluid and absolutely realistic. Evaluate the dexterity of your operators thanks to exercises in which EAPS allows you to work with a high level of precision.



#### **MODULAR HARDWARE**

The simulator's modular architecture allows the equipment to be quickly configurated in **shovel**, **excavator** (front or rear) or dumper mode.

This multi-machine function makes the simulator a versatile tool that can be adapted to several types of simultaneous training on the same hardware, thanks to which space can be saved and the amortization of the simulation equipment maximized.

### HARDWARE FEATURES

MINESIM AVR has **interchangeable modules** that make it customizable and adaptable to the configuration needs of each customer to suit the driving of **excavator**, **dumper and shovel loader**.



#### **CRAWLER EXCAVATOR**

It can be configured in **front excavator or backhoe** mode.

In both modes, the hall effect electronic **servo-controls** on the right and the left allow the control of the cab rotation, the height of the arm, the up and down movement of the gable and the movement of the bucket. The chains are controlled with two **pedals** that can be operated with the feet or connected to two **levers** that would allow the movement of the machine with the hands.

The crawler excavator also consists on two **control thrones** formed by buttons and controls important for the operation of the machine.



#### **DUMPER TRUCK**

In dumper mode the truck is driven with the accelerator and brake pedals. It also has an electric brake or retarder, which is more advisable for this vehicle than the traditional brake due to its weights and the loads it carries.

It has a steering column with steering wheel for driving and a **right throne** where the **lever** that controls the tipper is located. This lever allows this part of the vehicle to be lifted and the entire load to be unloaded in the area selected for this purpose.



#### LOADER SHOVEL

The loader is moved with accelerator and brake. It has a **servo-control** on the right side that controls the movement of the arm and the shovel.

For the configuration of this machine, there is a control throne on the right side that contains the most important buttons and commands for its proper functioning.



### SOFTWARE FEATURES

MINESIM AVR allows four machines to be driven: **crawler excavator (front and backhoe modes), loader and dumper truck.** Each machine has a tailor-made training plan, which enables the student to gradually assimilate the knowledge.



The training plan developed for the **crawler excavator** allows your students to practice doing a multitude of exercises:

- Unload to belt
- Unload in dumper
- Unload into well
- Circuit navigation. Slalom
- Adjusting the power of the machine to the job to be done.
- Excavation of slopes of different widths, in a straight line and in a zigzag.
- Excavation of slopes in dangerous areas, with risk of falls.
- Operation at night and in low visibility environments (excess dust, fog, rain).
- Etc.









The training plan developed for the **dumper truck** allows its students to practice with different types of activities:

- Using automatic retarder
- Use of cruise control
- Material unloading operation
- Emergency stop
- Evasive maneuver
- Mine traffic management
- Gauge control
- Recognition of tipper controls and dashboard reading.
- Practical positioning maneuvers for backhoe loaders and front loaders.
- Unloading of material into bathtub-type landfill.
- Traffic through open pit mine. Includes dangerous crossings and descents with retarder use.
- Operation at night and in low visibility environment (excess dest, fog, rain)
- Etc.





The training plan developed for the **loader shovel** allows students to practice different aspects:

- Using the floating shovel function
- Using the kick down function
- Proper gear management
- Traction control in complex environments
- Working with boluses
- Unloading by truck
- Discharge into well
- Working with traffic situations
- Recognition of machine controls and instrument panel reading
- Loading and unloading operations in dumper and hoppers at different heights
- Working with different typers of material, with different densities
- Traffic through open pit mine. Includes crossing
- Operation in risky situations, such as obstacles or low visibility environments
- Etc.







### INSTRUCTOR STATION AND SOCRATES

While the student is doing the practice, the instructor can observe him from different cameras, check the telemetry or interfere with it through the command sending system of the **instructor station**.

- Triggering malfunctions
- Modification of time of day / weather conditions
- Inclusion of risk situations or special conditions (traffic/pedestrians)
- Co-operative driving





The simulator recognizes the student through a biometric identification system and stores its result in **SOCRATES**, generating a report of each practice carried out for later analysis.

At all times, the simulator supervises the student's practice, monitoring the correct handling of the machine and sending messages when it detects that incorrect maneuvers are being carried out. This automatic supervision system can be used to compute the note of the exercise, indicating in the design of the exercise which infraction or errors will subtract points from the student's grade.



### SIMULATED MACHINES



#### **CRAWLER EXCAVATOR**

The MINESIM AVR excavator makes it possible to excavate low-level ground around an open-cast mine with the option of a front or backhoe excavator. The operator will be able to practice tasks such as filling a dumper-type truck or counter-rotating excavation, in different weather conditions and at different times of the day.

HARDWARE FEATURES		
LEFT SERVO CONTROL	arm extension / retraction and turning of the machine	
RIGHT SERVO CONTROL	elevation / lowering of the gable	
	extensión / retracción del cucharón	
PEDALS	bucket opening pedal, bucket closing pedal	
	right crawler control pedal	
	left crawler control pedal	
RIGHT THRONE	engine accelerator	
	tick over system	
	selection of propulsion mode	
	pilot cut off	
	horn, work lights, windscreen wipers	
	ignition key	
LEFT THRONE	heavy load system	
	engine power mode, gable mode	
	rotation priority mode / gable	
CONTROL PANEL	display, indicators and clocks	
	navigation arrows, emergency stop button	
	biometric identification system	

	GENERIC	model	HITACHI EX 5500-6
		fuel	diesel
		operating weight	522t
		bucket configuration	frontal / retro
		bucket capacity	29 m³
S		total width	10080 mm
JRE	NS	cabin height	8600 mm
DYNAMIC FEATURES	OISI	running gear length	9350 mm
E E	DIMENSIONS	running gear width	7400 mm
AM		shoe chains width	1400 mm
N/C		pressure on floor	232 kPa
		maximum speed	2,3 km/h
	PERFORMANCE	speed of turning	3,3 rpm
	MA	maximum slope	30°
	FOR	maximum pull strenght	18000 N
	PER	maximum ramp	23%
		engine power	2088 kw





#### **DUMPER TRUCK**

The MINESIM AVR dumper is a specific mining truck that allows large quantities of sand and rocks to be transported between different points of an open pit mine. The operator will be able to practice tasks of this machine such as the dumping of material, traffic circulation or the use of retarder on downhill slopes.

HARDWARE FEATURES		
STEERING WHEEL	steering wheel with 1100° rotation	
	turning indicators, lights and windshield wipers lever	
PEDALS	gas pedal	
	retarder brake pedal	
	service brake pedal	
RIGHT THRONE	FNR gearshift lever	
	box operating lever	
	ignition key	
	parking brake	
	warning	
	working lights	
CONTROL PANEL	screen	
	indicators	
	warning light	
	clocks	
	navigation arrows	
	emergency stop button	
	biometric identification system	

DYNAMIC FEATURES	GENERIC	model	HITACHI EH 5000 AC
		supply of energy	diesel- electric
		operating weight	500 t
		payload	296 t
	DIMENSIONS	total width	8160mm
		total height	7520mm
		total length	15490mm
N/C		maximum heigth box folded out	14500mm
	PERFORMANCE	maximum speed	56 km/h
		turning diameter	30 m
	PER	motor power	2125 kW



#### **LOADER SHOVEL**

The MINESIM AVR loader shovel allows you to work with different types of sand and rocks in the environment of an open pit mine. It has an exercise plan designed to increase operator productivity in real-life situations, such as unloading material into a hopper or a dumper truck.

HARDWARE FEATURES		
RIGHT SERVO CONTROL	raising / lowering the arm	
	bucket opening / closing	
PEDALS	accelerator pedal	
	service brake pedal	
RIGHT THRONE	engine accelerator	
	tick over system	
	selection of propulsion mode	
	pilot cut off	
	horn	
	work lights	
	windshield wipers	
	ignition key	
CONTROL PANEL	display, indicators	
	warning light	
	clocks	
	navigation arrows	
	emergency stop button	
	biometric identification system	

		model	KOMATSU WA900
	GENERIC	fuel	diesel
		operating weight	107t
S		ladle capacity	13m³
DYNAMIC FEATURES		total width	4585mm
EAT	SNO	total heigth	5275mm
<u> </u>	IENSIG	total length	14000mm
AM		turning radius	9200mm
N/N/N/N/N/N/N/N/N/N/N/N/N/N/N/N/N/N/N/		maximum heigth box folded out	9350mm
	ш	maximum speed	28 km/h
	PERFORMANCE	lifting time	11,2 s
	ERFOR	maximum torque / rpm	4089 Nm / 1300 rpm
		motor power	672 kW



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simulators manufactured countries with installed base

performed sessions



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